On Connected Two Communities

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Abstract

We say that there is a community structure in a graph when the nodes of the graph can be partitioned into groups (communities) such that each group is internally more densely connected than with the rest of the graph. However, the challenge is to specify what is to be dense, and what is relatively more connected (there seems to exist an analogous situation to what is a cluster in unsupervized learning). Recently, Olsen (2012) provided a general definition that seemed to be significantly more generic that others. We make two observations regarding such definition. (1) First, we show that finding a community structure with two equal size communities is NP-complete (UNIFORM 2 -COMMUNITIES). The first implication of this is that finding a large community seems intractable. The second implication is that, since this is a hardness result for $k = 2$, the UNIFORM k-COMMUNITIES problem is not fixed-parameter tractable when k is the parameter. (2) The second observation is that communities are not required to be connected in Olsen (2012)'s definition. However, we indicate that our result holds as well as the results by Olsen (2012) when we require communities to be connected, and we show examples where using connected communities seems more natural.

Keywords: Community detection, graph partitioning, complexity, parameterized complexity

1 Introduction

Researchers are now focusing on analyzing the community structure (Boccaletti et al. 2006, Lancichinetti et al. 2010) of graphs and finding so called communities or modules (intuitively these are groups of nodes that are more densely connected to each other than with the rest of the graph). Exploring communities in graphs is important (Lancichinetti et al. 2010) because 1) communities uncover the graph at a coarse level, for example, formulating realistic mechanisms for its genesis and evolution 2) communities provide a new aspect for understanding dynamic processes occurring in the graph and 3) communities reveal relationships among the nodes that are not apparent when inspecting the graph as a whole.

Recently, there has been a large research focus on community structures in graphs (Condon & Karp

2001, Fortunato 2010, Gargi et al. 2011, Kevin J. Lang et al. 2009). However, the main problem is how to define communities in the first place. This is the essential issue tackled by most papers on the topic which have appeared in the literature (Fortunato 2010, references therein). Here we consider the most recent definition of community structure introduced by Olsen (2012). This definition is inspired by the planted l-partition model, and the hierarchical random graph model introduced by Condon & Karp (2001). Olsen (2012) was able to justify why this becomes a more suitable (and formal) definition of community and initiated the study of the complexity of finding communities by showing that it is NP complete to decide if a group of nodes can be extended to a community in some community structure. Proceedings of the Thirty-Sixth Australasian Computer Science (ACSC 2013), Adelaide, V We controlled the Third Australia Computer Science Conference (ACSC 2013), Adelaide, Australia Computer Science Conference Conferenc

We introduce this generic notion of community using the following notation. Let Π be a partition of the vertices V of a graph $G = (V, E)$ (Π) $\{C_1, C_2, \ldots, C_k\}$, with $\emptyset \neq C_j \subset V$ for $j = 1, \ldots, k$ and $\bigcup_{j=1}^k C_j = V$, and $C_j \cap C_{j'} = \emptyset$ for $j \neq j'$). If $i \in V$, then we denote the part vertex i belongs to by Π_i . Let $i \in V$ be a vertex and $S \subset V$, then $N_i(S)$ is the number of vertices in S that are neighbors (adjacent) to the vertex i (a vertex is never considered adjacent to itself).

Definition 1.1 A community structure for an undirected connected graph $G = (\check{V}, E)$ is a partition Π of V such that

- 1. $|\Pi| \geq 2$ (we have at least 2 communities),
- 2. $|C| \geq 2$ for all $C \in \Pi$ (every community has at least 2 members) and
- 3. $\forall i \in V$, $\forall C \in \Pi$ the following holds

$$
\frac{N_i(\Pi_i)}{|\Pi_i| - 1} \ge \frac{N_i(C)}{|C|}.
$$
 (1)

Each set of the partition is called a community.

Olsen (2012) also showed that finding a community structure in a graph that does not contain S_n (the stars of *n* vertices), for $n \geq 3$ can be done in polynomial time. However, nothing could be said about the community structure, like if large communities could be found. Also, it was left open any claim whether finding community structures with few communities is tractable or not. Thus, we investigate here the question of finding a community structure with two communities. That ensures one community is large as it must include at least half of the vertices. It turns out that this investigation reveals one more aspect regarding Definition 1.1. We direct the reader to the observation that communities are not

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CRPIT Volume 135 - Computer Science 2013

required to be connected. That is, each part C is not required to be connected. Why we suggest communities be connected? Because it is hard not to consider the connected components of a disconnected "community" more naturally as communities in themselves. In fact, the lack of links (vs links to other parts of the graph) suggest the connected components are not to be placed together. We also consider uniform community structure, that is, all communities have the same size. The uniform community structure has gained importance due to its application for clustering and detection of cliques in social, pathological and biological networks (Patkar & Narayanan 2003).

We start with a discussion on the complexity of finding 2-COMMUNITIES. Why we look at the problem of two communities rather than the problem with k communities? Because by showing the problem with 2 communities is hard, we are showing the problem with k communities is also hard. Why we look at equal size communities? Because this forces the communities to be large. It seems in practice, the larger a community, the more interesting. We prove that when we require the communities to have equal size the problem is NP-complete. This result suggests that other lines of attack may be required. For example, a very successful avenue of attack has recently been the application of parameterized complexity theory. Such approach can lead to polynomial-time algorithms on the size of the input (at the cost of exponential-time complexity on the parameter, which can be small in practical settings). A first natural parameter is the number k of communities. That is, to consider the question whether, for a given graph G , there exists a community structure with exactly k communities. We call this problem k-COMMUNITIES. Because we will show that for $k = 2$, the problem UNIFORM k -COMMUNITIES (where communities are all of the same size) is NPcomplete, the problem UNIFORM k -COMMUNITIES is not fixed-parameter tractable when k is the parameter. In other words, it is unlikely to have an algorithm for this problem with $f(k) \cdot poly(|G|)$ time requirements, for some computable function f .

2 Uniform Two-Communities is hard

In this section, we formally define our problem and then show our main hardness result (Theorem 2.1). Our proof is inspired by a hardness result for a graph partitioning problem (Bazgan et al. 2010). We prove this results in several steps.

Uniform k-Communities *Instance*: A graph $G = (V, E)$. **Parameter:** An integer $k > 1$. **Question:** Does a community structure Π = $\{C_1, C_2, \ldots, C_k\}$ exist such that $|C_i| = |C_j|$ for $i, j = 1, \ldots, k?$

Theorem 2.1 UNIFORM 2-COMMUNITIES is NPcomplete.

UNIFORM 2-COMMUNITIES belongs to the class NP. Because, we can verify, in polynomial time, whether a partition of size two constitutes (with equal parts) a community structure. For the hardness part of the theorem, we give a polynomial reduction from a variant of the Clique problem to the Uniform 2-Communities problem. The version of the Clique problem that asks, for a given non-complete graph G of size n (n is even), whether there exists a complete subgraph of size at least $n/2$. This version of the CLIQUE problem is also NP -complete (Garey $\&$

Johnson 1979), and it is not hard to see that the version we will use (whether a graph has a clique of size $n/2$) is also NP-complete. Now we construct our reduction and we will show that every Yes-instance of the Clique problem maps to a Yes-instance of the UNIFORM 2-COMMUNITIES problem and vice versa.

Construction 1 Let $G = (V, E)$ be an instance of the CLIQUE problem with $V = \{v_1, v_2, \ldots, v_n\}$ and $E = \{e_1, e_2, \ldots e_m\}$ (with $|E| = m > 0$). Let p be the number of non-edges in G, that is $p = n \times (n 1/2 - m$. The value of p is at least one, as the graph \tilde{G} is a non-complete graph. Suppose we label the nonedges in G by ne_1, \ldots, ne_p . We construct an instance $G^{\prime\prime} = (V'', \check{E}'')$ of the 2-COMMUNITIES problem as follows. The vertex set V'' consists of four disjoint sets, $F, T, V \text{ and } V'$. That is, $V'' = F \cup T \cup V \cup V'$. The set \overrightarrow{V} is the original set of vertices in the instance of the CLIQUE problem; the set $V' = \{v'_1, \ldots, v'_n\}$ consists of as many mirror vertices as in the original set V of vertices. The set $F = \{f_1, \ldots, f_{2p+1}\},\$ has two vertices f_{2l} , f_{2l+1} for each non-edge nel with $l = 1, \ldots, p$ and f_1 is an additional vertex. The set $T = \{t_1, \ldots, t_{2p+1}\}$ also has two vertices t_{2l}, t_{2l+1} for each non-edge in the original instance of the CLIQUE problem, and also t_1 is an additional vertex.

We now describe the set of edges E'' . The set E of original edges among vertices in V is in E'' ; that is $E \subset E''$. In the new instance, F and T are two cliques of size $2p+1$ (that is, in E'', all vertices of F are connected among themselves and also in E'' , all vertices of T are connected among themselves). For $j = 1, \ldots, n, \; (v_j', \; v_j)$ is in $E''.$ The edge set E'' contains some additional edges as follows:

- Each vertex $t \in T$ connects to all vertices of V.
- Each vertex $f \in F$ connects to all vertices of V, unless
	- f is of the form f_{2l} or f_{2l+1}
	- $-$ and $ne_l = (v_i, v_j)$ is the missing edge (with $i < j$) in G corresponding to the pair $(f_{2l},f_{2l+1}).$

In this case, the vertex f_{2l} connects to every vertex in $V \setminus \{v_j\}$, and f_{2l+1} connects to every vertex in $V \setminus \{v_i\}.$

Finally, the edge (f_1, t_1) is in E'' .

Note the following about this construction. First, the degree of all vertices in V' is one, as these vertices are only connected to their mirror vertices. Second, the degree of every vertex $t \neq t_1$ in T is $|V|+|T|-1 =$ $n + 2p$, and the degree of t_1 is $|V| + |T| = n + 2p + 1$. This is because t is in clique T (degree $|T|-1$) and it is connected to each vertex in V and t_1 is additionally connected to f_1 . Third, the degree of every vertex $f \in F$ is at least $|F| - 1$ as it belongs to the clique F. The vertex f_1 has degree $|F| + |V|$, but the other vertices in F have degree $|F| + |V| - 2$, as each of these vertices looses one connection to one vertex in V that is an endpoint of a non-edge.

Figure 1 provides a more specific example of the reduction. Clearly, this construction can be performed in polynomial time. We only need to show that a Yesinstance of the first problem maps to a Yes-instance of the second problem and vice versa.

Proposition 2.2 A YES-instance of the CLIQUE problem maps to a YES-instance of the UNIFORM 2-COMMUNITIES problem.

Figure 1: The dotted lines mean that there is no edge between the two end points of the line. A branch of four edges at f_1 and each vertex of T mean those vertices connect to all vertices of V.

Proof: First, assume that the graph G has a clique C of size $n/2$. We define a partition of size two of the graph G'' by considering the first set as Π_1 = $F \cup C \cup C'$ where $C' = \{v'_i : v_i \in C\}$ and the second set as $\Pi_2 = T \cup \overline{C} \cup \overline{C}'$, where $\overline{C} = V - C$ and $\overline{C}' =$ $\{v_i': v_i \in \overline{C}\}\.$ We show these two sets constitute a community structure of size two.

We must verify Inequality (1) for the three types of vertices that appear in $\Pi_1 = F \cup C \cup C'$ and also for the three types of vertices in $\Pi_2 = T \cup \overline{C} \cup \overline{C'}$. We start with Π_1 , and in particular with vertices in C. Then, vertices in F (this will require three cases) and then C' . When dealing with Π_2 , we sill start with \bar{C} , then T and finally \overline{C} .

Let c be a vertex in the clique C . We consider $x_c = n - 1 - N_c(V)$, that is the number of non-edges in the graph G with one end-point in the vertex c . Then, by construction, the vertex c is not linked to x_c vertices of the clique F. Since C is a clique of size $n/2$ in V, then it involves at least half of the vertices of V, that is $|C| \geq |\bar{C}|$. Also, by construction we have $|F| = |T|$. We can then see that $N_c(\Pi_1)$ equals $|F| + |C| - x_c$, because the vertex c connects to $|C| - 1$ vertices of the clique C, its mirror c' and $|F| - x_c$ vertices in F. Therefore, we have

$$
\frac{N_c(\Pi_1)}{|\Pi_1| - 1} = \frac{|F| + |C| - x_c}{|\Pi_1| - 1}
$$
\n
$$
\geq \frac{|T| + |\bar{C}| - x_c}{|\Pi_1| - 1}
$$
\n
$$
> \frac{|T| + |\bar{C}| - x_c}{|\Pi_1|} = \frac{|T| + |\bar{C}| - x_c}{|\Pi_2|}.
$$

Now, we compute $N_c(\Pi_2)$. The vertex c in the clique C connects to every vertex in T and to every vertex v on C unless (c, v) is a non edge. Moreover, all nonedges with an endpoint in c must have an endpoint in \overline{C} as C is a clique. Therefore, we have

$$
\frac{N_c(\Pi_2)}{|\Pi_2|} = \frac{|T| + |\bar{C}| - x_c}{|\Pi_2|}.
$$

This implies that the vertex c satisfies Inequality (1) .

Now we need to show that every vertex in F also satisfies Inequality (1) since the second type of vertex in Π_1 are the vertices in F.

Consider $f \in F$. According to our construction the size of the clique F is at least three $(|F| \geq 3)$ and we will face the following cases.

Case 1: $f \neq f_1$, and f connects to every vertex in C.

In this case $N_f(\Pi_1)$ equals $|F| - 1 + |C|$, since the vertex f connects to every vertex in C. Also,
we have $|\bar{C}| \ge N_f(\Pi_2)$, therefore

$$
\begin{array}{rcl} \frac{N_f(\Pi_1)}{|\Pi_1| - 1} & = & \frac{|F| - 1 + |C|}{|\Pi_1| - 1} \\ & \geq & \frac{|F| - 1 + |\bar{C}|}{|\Pi_1| - 1} \\ & > & \frac{|F| - 1 + |\bar{C}|}{|\Pi_1|} \\ & = & \frac{|F| - 1 + |\bar{C}|}{|\Pi_2|} \\ & > & \frac{|\bar{C}|}{|\Pi_2|} \geq \frac{N_f(\Pi_2)}{|\Pi_2|} . \end{array}
$$

Case 2: The vertex f connects to every vertex in C except one.

We recall that the degree of every vertex in F that is not f_1 is $|F|+|\breve{V}|-2$. Since $|F|\geq 3$, then we have

$$
\frac{N_f(\Pi_1)}{|\Pi_1| - 1} = \frac{|F| - 1 + |C| - 1}{|\Pi_1| - 1}
$$
\n
$$
\geq \frac{|F| - 1 + |\bar{C}| - 1}{|\Pi_1| - 1}
$$
\n
$$
> \frac{|F| - 2 + |\bar{C}|}{|\Pi_1|} = \frac{|F| - 2 + |\bar{C}|}{|\Pi_2|}
$$
\n
$$
\geq \frac{|\bar{C}|}{|\Pi_2|} = \frac{N_f(\Pi_2)}{|\Pi_2|}.
$$

Case 3: $f = f_1$.

 N

 N

According to the construction, f connects to every vertex in C and also connects to t_1 . Hence, we have

$$
\frac{N_f(\Pi_1)}{|\Pi_1| - 1} = \frac{|F| - 1 + |C|}{|\Pi_1| - 1}
$$
\n
$$
\geq \frac{|F| - 1 + |\bar{C}|}{|\Pi_1| - 1}
$$
\n
$$
> \frac{|F| - 1 + |\bar{C}|}{|\Pi_1|}
$$
\n
$$
= \frac{|F| - 1 + |\bar{C}|}{|\Pi_2|}
$$
\n
$$
\geq \frac{1 + |\bar{C}|}{|\Pi_2|} \geq \frac{N_f(\Pi_2)}{|\Pi_2|}
$$

.

The last type of vertex in Π_1 that we check for Inequality (1) belongs to C' , but these vertices have degree 1 in Π_1 and degree zero in Π_2 , so this is immediate.

To complete the proof that we have a YESinstance of 2 -COMMUNITIES we need to establish Inequality (1) for the vertices in Π_2 . We start by showing that Inequality (1) holds for every vertex c in \bar{C} .

First, $N_c(\Pi_2) = |T| + 1 + N_c(\bar{C})$, since c connects to all vertices in T , all its neighbors in \overline{C} and also connects to its mirror c' . Second, assume x_c is the number of non-edges in \overline{C} with endpoint in c, then we have $N_c(\Pi_2) = |\overline{T}| + 1 + |\overline{C}| - 1 - x_c = |T| + |\overline{C}| - x_c.$ Third, if there exists a missing edge (e, v) with $v \in$ \overline{C} , corresponding to this missing edge, there exists exactly a missing edge between c and a vertex $f \in F$. Therefore, $N_c(\Pi_1)$ equals $|F| - x_c + N_c(C)$. Since $|\overline{C}| = |C|$ and $|\overline{C}| \geq N_c(C)$, then we have

$$
\frac{N_c(\Pi_2)}{|\Pi_2| - 1} = \frac{|T| + |\bar{C}| - x_c}{|\Pi_2| - 1}
$$
\n
$$
\geq \frac{|F| + N_c(C) - x_c}{|\Pi_1| - 1}
$$
\n
$$
> \frac{|F| + |C| - x_c}{|\Pi_1|}
$$
\n
$$
= \frac{N_c(\Pi_1)}{|\Pi_1|}.
$$

We now argue for the second type of vertices in Π ₂. We show that every vertex *t* in *T* satisfies Inequality (1). Since $|\Pi_1| = |\Pi_2|$, |*T*| ≥ 3 and |*C*| = |*C*| we have for every $t \neq t_1$

$$
\frac{N_t(\Pi_2)}{|\Pi_2| - 1} = \frac{|T| + |\bar{C}| - 1}{|\Pi_2| - 1}
$$

=
$$
\frac{|T| + |C| - 1}{|\Pi_1| - 1}
$$

>
$$
\frac{|T| + |C| - 1}{|\Pi_1|}
$$

>
$$
\frac{|C|}{|\Pi_1|}
$$

\$\geq\$
$$
\frac{N_t(\Pi_1)}{|\Pi_1|}.
$$

Similarly, for $t = t_1$ we have

$$
\frac{N_t(\Pi_2)}{|\Pi_2| - 1} = \frac{|T| + |\bar{C}| - 1}{|\Pi_2| - 1}
$$

=
$$
\frac{|T| + |C| - 1}{|\Pi_1| - 1}
$$

>
$$
\frac{|T| + |C| - 1}{|\Pi_1|}
$$

\$\geq\$
$$
\frac{|C| + 1}{|\Pi_1|}
$$

\$\geq\$
$$
\frac{N_t(\Pi_1)}{|\Pi_1|}.
$$

And to complete all vertices of Π_2 we consider the mirror vertices in \bar{C}' , but again these vertices have degree one to their community Π_2 and zero to the other part Π_1 , so trivially they satisfy Inequality (1).

Therefore, a Yes-instance of the Clique problem maps to a YES-instance of the UNIFORM

2-COMMUNITIES problem.

Now we show that the reverse is true.

Proposition 2.3 A YES-instance of the UNIFORM 2-Communities problem maps to a Yes-instance of the CLIQUE problem.

Suppose $I = (G'', \Pi_1, \Pi_2)$ is a YES-instance of the Uniform 2-Communities problem. We justify the following observations to show the pre-image of I is a Yes-instance of the Clique problem.

Observation 2.4 (about mirror vertices): In each YES-instance of 2-COMMUNITIES, the mirror vertices v'_j must be in the same community as v_j , with $j=1,\ldots,n$.

Proof: If a mirror vertex v' is in community Π_1 , and its corresponding vertex v is in community $\Pi_2 \neq \Pi_1$, then $N_{v'}(\Pi_1) = 0$, while $N_{v'}(\Pi_2) > 0$. This contradicts that the vertex v' must satisfy Inequality (1).

Observation 2.5 The set T can not be cut by the community structure.

Proof: (by contradiction) Suppose T is divided in (T_1, T_2) with $T_i \subseteq \Pi_i$ and $i = 1, 2$. Also assume that the set V is cut in (V_1, V_2) with with $V_i \subseteq \Pi_i$ and $i = 1, 2$, where V_1 and V_2 could be empty. Moreover, assume that F is divided in (F_1, F_2) with $F_i \subseteq \Pi_i$ and $i = 1, 2$. We will face the following cases where each one leads to a contradiction.

Case 1: $T_1 = \{t_1\}$ and $F_1 = \{f_1\}.$

In this case $|T_2|$ is $|T| - 1$ and $|F_2| = |F| - 1$. Therefore, $|T_2|$ is equal to $|F_2|$ and both are equal to $|T| - 1$ because $|T| = |F|$. Since Π is a community structure, then every $t \in T_2$ must satisfy Inequality (1). But,

$$
\frac{N_t(\Pi_2)}{|\Pi_2| - 1} = \frac{|T_2| - 1 + |V_2|}{|F_2| + 2|V_2| + |T_2| - 1}
$$

=
$$
\frac{(|T| - 1) - 1 + |V_2|}{(|F| - 1) + 2|V_2| + (|T| - 1) - 1}
$$

=
$$
\frac{|T| + |V_2| - 2}{2|T| + 2|V_2| - 3} < \frac{1}{2},
$$

 $1 + |V|$

and

$$
\frac{N_t(\Pi_1)}{|\Pi_1|} = \frac{1+|V_1|}{2|V_1|+2} = \frac{1}{2}.
$$

This statement contradicts the vertex t must satisfy Inequality (1).

Case 2: $T_1 = \{t_1\}$ and $f_1 \in F_2$.

 $Nf(TT)$

The neighbors of the vertex t_1 in Π_1 are all vertices in V_1 as $T_1 = \{t_1\}$. Also, the neighbors of the vertex t_1 in Π_2 are all vertices in T_2 , with also all vertices in V_2 and f_1 . Therefore, we have

$$
\frac{N_{t_1}(\Pi_1)}{|\Pi_1| - 1} = \frac{|T_1| - 1 + |V_1|}{|F_1| + 2|V_1| + |T_1| - 1}
$$

=
$$
\frac{1 - 1 + |V_1|}{|F_1| + 2|V_1| + 1 - 1}
$$

=
$$
\frac{|V_1|}{|F_1| + 2|V_1|}
$$

$$
\leq \frac{1}{2}.
$$

Since $|T_1| = 1$, $|T_2| = |T| - 1$ and $|T| + 1 > |F| \ge$ $|F_2|$, then we have

$$
\frac{N_{t_1}(\Pi_2)}{|\Pi_2|} = \frac{|T_2| + |V_2| + 1}{|T_2| + 2|V_2| + |F_2|} > \frac{1}{2}.
$$

This statement contradicts the fact that the vertex t_1 must satisfy Inequality (1).

Case 3: $T_1 = \{t_1\}$ and $|F_1| \geq 2$.

Case 1 and Case 2 resulted in if $T_1 = \{t_1\}$, then the vertex f_1 must be in F_1 and $|F_1| \geq 2$. Now we consider the vertex t_1 to show that it violates Inequality (1). First, the neighbors of the vertex t_1 in Π_1 are all vertices in V_1 and f_1 . Second, the size of $|F_1| \geq 2$, therefore we have

$$
\frac{N_{t_1}(\Pi_1)}{|\Pi_1| - 1} = \frac{|V_1| + 1}{|F_1| + 2|V_1| + |T_1| - 1}
$$

=
$$
\frac{|V_1| + 1}{|F_1| + 2|V_1|}
$$

$$
\leq \frac{1}{2}.
$$

On the other hand, $|F_1| \geq 2$ implies that $|F_1|$ + $|F_2| \geq |F_2| + 2$. The latter inequality implies that $|T| = |F| > |F_2| + 1$. Then, we have

$$
|T| > |F_2| + 1
$$

\n
$$
\Rightarrow |T| - 1 > |F_2|
$$

\n
$$
\Rightarrow |T_2| > |F_2|
$$

\n
$$
\Rightarrow 2|T_2| + 2|V_2| > |T_2| + 2|V_2| + |F_2|.
$$

The most right inequality implies that

$$
\frac{N_{t_1}(\Pi_2)}{|\Pi_2|} = \frac{|V_2| + |T_2|}{|T_2| + 2|V_2| + |F_2|} > \frac{1}{2}
$$

.

This statement shows that the vertex t_1 violates Inequality (1).

Case 4: $\{t_1, t\} \subseteq T_1$ where $t \neq t_1$.

The above cases imply that the set T_1 must contain another vertex $t \neq t_1$. Since the vertex $t \in T_1$ must satisfy Inequality (1), then we have

$$
\frac{N_t(\Pi_1)}{|\Pi_1| - 1} = \frac{|T_1| + |V_1| - 1}{|\Pi_1| - 1}
$$
\n
$$
\geq \frac{N_t(\Pi_2)}{|\Pi_2|}
$$
\n
$$
= \frac{|T_2| + |V_2|}{|\Pi_2|}. \tag{2}
$$

Also, each vertex t' in T_2 must satisfy Inequality (1), therefore,

$$
\frac{N_{t'}(\Pi_2)}{|\Pi_2| - 1} = \frac{|T_2| + |V_2| - 1}{|\Pi_2| - 1}
$$
\n
$$
\geq \frac{N_{t'}(\Pi_1)}{|\Pi_1|}
$$
\n
$$
= \frac{|T_1| + |V_1|}{|\Pi_1|}. \tag{3}
$$

From Inequality (2) we get

$$
|\Pi_2|(|T_1| + |V_1|)
$$

\n
$$
\geq (|\Pi_1| - 1)(|T_2| + |V_2|) + |\Pi_2|. \qquad (4)
$$

From Inequality (3) we get

$$
|\Pi_1|(|T_2|+|V_2|-1) \ge (|\Pi_2|-1)(|T_1|+|V_1|),
$$

or equivalently

$$
|\Pi_1|(|T_2| + |V_2| - 1) \geq |\Pi_2|(|T_1| + |V_1|) - (|T_1| + |V_1|). \quad (5)
$$

Combining Inequality (4) and Inequality (5) we arrive at

$$
|\Pi_1| + |\Pi_2| \le (|T_1| + |T_2|) + (|V_1| + |V_2|).
$$

This inequality contradicts to the fact that F is not empty.

Observation 2.6 The set F can not be cut by the community structure.

Proof: Assume that F is cut into (F_1, F_2) where $F_1 \subseteq$ $\Pi_1, F_2 \subseteq \Pi_2$ and $F_1 \neq \emptyset$. Also assume that the original set V is cut into (V_1, V_2) with $Vi \subseteq \Pi_i$ and $i =$ 1, 2, where V_1 and V_2 could be empty. Moreover, since T can not be split, without loss of generality we can assume that $\Pi_1 = V_1 \cup V_1' \cup F_1$, $\Pi_2 = V_2 \cup V_2' \cup T \cup F_2$. We show that F_2 is empty or we have a contradiction. Proceeding the Third-1 Direct Definition of the Third-1 Direct Definition Computer Science (ACSC 2013), Adelain Computer Science (ACSC 2013), Adelain Computer Science (ACSC 2013), Adelain Computer Science (ACSC 2013), Ade

Assume that F_2 is not empty and let $f \in F_2$. Then we will face the following cases.

Case 1: $f = f_1$.

The neighbors of vertex f_1 in Π_2 are all vertices in V_2 , plus all vertices in $\tilde{F}_2-\{f_1\}$ and the vertex t_1 . Therefore, we have

$$
\frac{N_{f_1}(\Pi_2)}{|\Pi_2|-1} = \frac{|F_2| + |V_2|}{|F_2| + 2|V_2| + |T| - 1} \le \frac{1}{2}.
$$

Similarly, the neighbors of the vertex f_1 in Π_1 are all vertices in V_1 , plus all vertices in F_1 , therefore,

$$
\frac{N_{f_1}(\Pi_1)}{|\Pi_1|} = \frac{|F_1| + |V_1|}{|F_1| + 2|V_1|} > \frac{1}{2}.
$$

This statement shows that the vertex f_1 violates Inequality (1), so it is a contradiction.

Case 2: $f \neq f_1$ and f does not connect to a vertex of V_2 .

The neighbors of the vertex f in Π_2 are all vertices in V_2 except one, plus all vertices in $F_2 - \{f\}$, hence,

$$
\frac{N_f(\Pi_2)}{|\Pi_2|-1} = \frac{|F_2|-1+|V_2|-1}{|F_2|+2|V_2|+|T|-1} < \frac{1}{2}.
$$

Similarly, the neighbors of the vertex f in Π_1 are all vertices in V_1 , plus all vertices in F_1 , therefore,

$$
\frac{N_f(\Pi_1)}{|\Pi_1|} = \frac{|F_1| + |V_1|}{|F_1| + 2|V_1|} > \frac{1}{2}.
$$

This contradicts the fact that the vertex f must satisfy Inequality (1).

Case 3: $f \neq f_1$, f does not connect to a vertex of V_1 and $|F_1| \geq 2$.

The neighbors of the vertex f in Π_2 are all vertices in V_2 , plus all vertices in $F_2 - \{f\}$, hence,

$$
\frac{N_f(\Pi_2)}{|\Pi_2| - 1} = \frac{|F_2| - 1 + |V_2|}{|F_2| + 2|V_2| + |T| - 1} < \frac{1}{2}
$$

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Similarly, the neighbors of the vertex f in Π_1 are all vertices in V_1 except one, plus all vertices in F_1 . Moreover, the size of $|F_1| \geq 2$, therefore,

$$
\frac{N_f(\Pi_1)}{|\Pi_1|} = \frac{|F_1| + |V_1| - 1}{|F_1| + 2|V_1|} \ge \frac{1}{2}.
$$

Similar to Case 1 above, we have a contradiction that the vertex f violates Inequality (1).

Case 4: If $f \neq f_1$, f does not connect to a vertex of V_1 and $|F_1| < 2$.

Since F_1 is not empty, we must have $|F_1| = 1$, and by Case 1, $F_1 = \{f_1\}$, while $|F_2| = |F|-1$. Moreover, the vertex f_1 must satisfy Inequality (1). Therefore, we have

$$
\frac{N_{f_1}(\Pi_1)}{|\Pi_1|-1} = \frac{|V_1|}{1+2|V_1|-1} = \frac{1}{2}.
$$

Now, to find the value of $N_{f_1}(\Pi_2)/|\Pi_2|$, we note that f_1 is adjacent to all the vertices in F_2 , all the vertices in V_2 and t_1 . Moreover, $|F_2| = |T| - 1$. Thus,

$$
\frac{N_{f_1}(\Pi_2)}{|\Pi_2|} = \frac{|V_2| + |F_2| + 1}{2|V_2| + |F_2| + |T|}
$$

=
$$
\frac{|V_2| + |T|}{2|V_2| + 2|T| - 1}
$$

>
$$
\frac{|V_2| + |T|}{2|V_2| + 2|T|}
$$

=
$$
\frac{1}{2}.
$$

This is a contradiction since the vertex f_1 must satisfy Inequality (1) for a 2-community. \Box

Observation 2.7 The set F and and the set T do not belong to a same community.

Proof: (by contradiction) Assume V is cut in (V_1, V_2) . Also, assume $\Pi_1 = F \cup T \cup V_1 \cup V_1'$ and $\Pi_2 = V_2 \cup V_2'$. Consider a vertex $t \neq t_1$ in T. The neighbors of the vertex t in Π_1 are all vertices in V_1 , plus all vertices in $T - \{t\}$. Similarly, the neighbors of the vertex t in Π_2 are only all vertices in \tilde{V}_2 . Since (Π_1, Π_2) is a community structure, then the vertex t must satisfy Inequality (1) . Therefore, we have

$$
\frac{N_t(\Pi_1)}{|\Pi_1| - 1} = \frac{|V_1| + |T| - 1}{|F| + 2|V_1| + |T| - 1} \ge \frac{N_t(\Pi_2)}{|\Pi_2|} = \frac{|V_2|}{2|V_2|}.
$$

By simplifying the the above inequality we arrive at

$$
\frac{|V_1| + |T| - 1}{|F| + 2|V_1| + |T| - 1} \ge 1/2.
$$

Now the above inequality implies that

$$
2 \cdot (|V_1| + |T| - 1) \ge |F| + 2|V_1| + |T| - 1,
$$

and hence

$$
2 \cdot |V_1| + 2 \cdot |T| - 2 \ge |F| + 2|V_1| + |T| - 1.
$$

Since $|T| = |F|$, the last inequality implies that $-2 \ge -1$, which is a contradiction. Therefore, T and F are not in a same community. \Box **Observation 2.8** If (V_1, V_2) is a cut of V based on community structure (Π_1, Π_2) , then Π_1 = $F \bigcup V_1 \bigcup V'_1$, $\Pi_2 = T \bigcup V_2 \bigcup V'_2$ and V_1 is a clique.

Proof: (by contradiction) Assume V_1 is not a clique. Therefore, there exist a missing edge between two vertices of V_1 . Suppose $v \in V_1$ is one of the end points of the mentioned missing edge. Assume x_v is the number of missing edge in V_1 with one end in v. Clearly $x_v \geq 1$. Also assume that y_v is the number of missing edge in V_2 with one end in v .

Since (Π_1, Π_2) is a community structure, the vertex v must satisfy Inequality (1) , therefore we have

$$
\frac{N_v(\Pi_1)}{|\Pi_1| - 1} = \frac{(|V_1| - 1) - x_v + |F| - (x_v + y_v)}{|\Pi_1| - 1}
$$
\n
$$
\geq \frac{N_v(\Pi_2)}{|\Pi_2|}
$$
\n
$$
= \frac{|V_2| - y_v + |T|}{|\Pi_2|}. \tag{6}
$$

Since $|\Pi_1| = |\Pi_2|$, therefore $|V_1| = |V_2|$. Now we simplify Inequality (6) as follows.

$$
|\Pi_2|((|V_1|-1)-x_v+|F|-(x_v+y_v))
$$

\n
$$
\geq (|\Pi_1|-1)(|V_2|-y_v+|T|).
$$

Now we substitute $|\Pi_1|$ with $|\Pi_2|$, $|F|$ with $|T|$ and $|V_1|$ with $|V_2|$ as they are equal to each other. Therefore, we get

$$
|\Pi_2|((|V_2|-1)-x_v+|T|-(x_v+y_v))
$$

\n
$$
\geq (|\Pi_2|-1)(|V_2|-y_v+|T|).
$$

After canceling equal values from the both sides of the inequality and simplifying it, then we arrive at

$$
|V_2| + |T| \geq |\Pi_2| + 2 \cdot x_v |\Pi_2|.
$$

But, the latter inequality represents a contradiction since $x_v \geq 1$ and the value of the left side of the above inequality is in fact less than $|\Pi_2|$. Therefore V_1 is a clique.

Observation 2.9 The size of V_1 is at least $n/2$.

Proof: Observation 2.8 shows that V_1 is a clique. Also we know that $|\Pi_1| = |\Pi_2|$, therefore, $|V_1| = |V_2|$.
Hence, the size of $|V_1| = n/2$.

3 Some observations on the definition of community structure

As we alluded in the introduction, our aim was to investigate when can we find a large community within a community structure. Thus, we focused on the 2-Communities problem since this ensures one community is large as it must include half of the vertices of the underling graph. However, we discovered that requesting connectivity for each community changes the problem. According to Definition 1.1, communities are not required to to be connected. That is, each community \overline{C} in the community structure is not required to be connected.

Observation 3.1 There are graphs that do not have a 2-community structure, if we demand that each community must be connected; but have a 2 community structure under Definition 1.1.

Figure 2: This graph has a 2-community structure, nodes in the purple oval is one community and nodes in the green are the other. But the purple community is disconnected. There is no 2-community structure if we require the communities to be connected.

Proof: For example, the graph in Figure 2 has a non-connected community in a 2-community structure, but it does not have a 2-community structure where both communities are connected. It does have a community structure with three communities. \Box

One can examine Olsen (2012)'s original proof about whether there exists a community structure where a given set S of vertices is in one community. We discovered that the proof also shows the problem to be NP-complete when we add the condition that each community shall be connected. Also, Olsen's algorithm (Olsen 2012, Theorem 2) for computing a sample community structure always returns connected communities in the structure.

We find it more natural that communities should be connected. And thus, propose that Definition 1.1 should require that each community be connected.

Olsen's algorithm (Olsen 2012, Theorem 2) also has the unfortunate circumstance that it may produce very small (and thus a large number) of communities. The algorithm uses a polynomial number of local-search improvements among certain partitions of the input graph G. Each step requires polynomial time and the climb on the values of the objective function finishes with a community structure. The output of his algorithm depends to the initial state and, for example, if we consider the graph in Figure 3 the algorithm finishes with many communities, each of size three; although the graph accepts a 2 community (with connected communities). That is, if we apply his algorithm to this graph by considering the edge $\{v, w\}$ and the edge $\{v', w'\}$ as an initial stage, then it will produce a community structure with many small communities. Therefore, this algorithm may not produce a community structure which has far more communities $(O(n))$ when the graph actually accepts a constant number. Thus, it is not a good algorithm to approximate within a constant ratio the largest community or the smallest number of communities.

Figure 3: The left side illustrates the schema of the input graph; many S_{3} (stars of three vertices, arranged in a cycle). The right side illustrates a community structure found by applying Olsen's algorithm (Olsen 2012) with an initial state consisting of the edge $\{v, w\}$ and the edge $\{v', w'\}.$

4 Classes of graphs with 2-communities

The example of Figure 3 enables us to reflect on what graphs accept 2-communities. In particular, since a community is a concept close to a cluster or a region of high density, a community structure with 2 communities must imply some low density between the communities. We can establish a relation between the notion of a cut in a graph and the notion of a 2 community structure. A cut in a graph $G=(V, E)$ is a partition (Π_1, Π_2) of vertices of G, and is called balanced if $|\Pi_1| = |\Pi_2|$. The set of edges whose end points are in different subsets of the partition is called a cut set. A min-cut is a cut with the smallest cut-set size (and can be found in polynomial time, although it might not be balanced). Figure 4 illustrates a mincut of size two. Proceeding of the Thirty-Sixth Australasian Computer Science (ACSC 2013), Adelais Computer Science (Apple 1987), Adelais Computer Science Conference (Apple 1987), Adelais Computer Science Conference Conference Conference

Figure 4: A min cut of size two.

We show that a balanced min-cut of a graph G constitutes a 2-community structure.

Observation 4.1 If (Π_1, Π_2) is a cut of size two of a graph G with cut-set S, then every vertex that is not an endpoint of an edge in S satisfies Inequality (1).

This is immediate. Every vertex $v \in \Pi_i$, that is not an endpoint of an edge in the cut-set S , has no connections to the other side. Thus, the value of $N_v(\Pi_j)$ with $j \neq i$ is zero.

Observation 4.2 If (Π_1, Π_2) is a minimum cut of graph G with $|\Pi_1| = |\Pi_2|$, then (Π_1, Π_2) forms a 2community structure.

Proof: Based on Observation 4.1, we only need to show that every vertex in the cut-set satisfies Inequality (1). Assume a vertex $v \in \Pi_1$ is an endpoint of an edge in the cut-set S . The number of neighbors of vertex v in the set Π_1 is equal or greater that the number of neighbors of vertex v in the set Π_2 . Otherwise, we can make an smaller cut-set by moving vertex v to the set Π_2 (contradicting the fact that the size of S is minimum among all cut-sets). Therefore,

$$
\frac{N_v(\Pi_1)}{|\Pi_1| - 1} \ge \frac{N_v(\Pi_2)}{|\Pi_2|},
$$

since the size of Π_1 is equal to the size of Π_2 . That
is the vertex *v* satisfies Inequality (1) is the vertex v satisfies Inequality (1) .

Corollary 4.3 Paths and cycles with even number of vertices have a 2-communities structure.

The above corollary can be extended to the paths and cycles with odd number of vertices.

Lemma 4.4 The 2-COMMUNITIES problem for graphs with maximum degree two and $|\tilde{V}| \geq 3$ can be solved in polynomial time.

Proof: Let $G = (V, E)$ be a graph with maximum degree two. If G is not a connected graph, then consider

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any connected component Π_1 as one community and $\Pi_2 = V - \Pi_1$ as the second community. The partition (Π_1, Π_2) forms a 2-community structure since there is no edge between the two sets. Thus, based on Observation 4.1, all vertices satisfy Inequality (1).

Assume now that G is a connected graph. Since the maximum degree is at most two and the graph is connected, the graph G is a path or a cycle. We can construct a two communities as follows.

- **Case 1:** The graph G is a path. We pick a vertex v of degree one and add all vertices in a path of length $\lceil |\check{V}|/2 \rceil$ from v into a set Π_1 . The rest of vertices is placed in a set Π_2 . It is not hard to see that all vertices in Π_1 , and Π_2 satisfy Inequality (1). Hence (Π_1, Π_2) is a 2-community structure.
- **Case 2:** G is a cycle. We pick a vertex v of the cycle and add all vertices in a path of length $\lceil |V|/2 \rceil$ from v into a set Π_1 . Again, the rest of vertices is placed in a set Π_2 . A similar argument to Case 1 shows that (Π_1, Π_2) is a 2-community structure.

 \Box

5 Conclusion and open problems

We studied the computational complexity of the uniform k -COMMUNITIES problem. We showed that this problem is NP-complete even for $k = 2$. The complexity of the problem is not known if we drop the uniformity (size of all communities are equal) condition as in the k -COMMUNITIES problem. This leads to observations for detecting a community structure of size two. We also showed that the known algorithm (Olsen 2012) for finding a community structure may find a solution that is very far from an optimal solution to the 2-COMMUNITIES problem. Moreover, we observed that there may exist graphs where some communities are not connected. Since requiring all communities to be connected is consistent with previous work, we suggest the definition should incorporate this requirement.

Our work here leads to several interesting open problems for finding a community structure with a specific property. We list some of them.

- Problem 1: Determine the computational complexity of the uniform k -COMMUNITIES problem on different classes of graphs, such as planar graphs and regular graphs.
- Problem 2: Determine the computational complexity of the k -COMMUNITIES problem.
- Problem 3: Determine the computational complexity of finding a community structure with one community of size at least k .

Another interesting connection of the k-Communities problem seems to be a relatively similar problem in the literature which is called the SPARSEST CUTS problem. A sparest cut of a graph $G=(V, E)$ is a partition $(V_1, V \setminus V_1)$ having the minimum density

 $|cut\text{-}set(V_1)|/|V_1||V \setminus V_1|$

among all partitions in the graph, where

cut-set $(V_1) = \{e = \{u, v\} \in E \mid u \in V_1 \text{ and } v \notin V_1\}.$

The SPARSEST CUTS problem is NP-hard; however, it can be solved in polynomial time on trees and planar triconnected graphs (Matula & Shahrokhi 1990). It is not hard to see that in paths and in cycles a sparsest cut is also a 2-community structure and vice versa. However, it would be interesting to know on what graph classes the concept of 2-community structure and of sparest-cut are identical.

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